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2019

Conference and Workshop Papers

[C1] E Vespa, N Funk, PH Kelly and S Leutenegger,
Adaptive-resolution octree-based volumetric SLAM,
2019 International Conference on 3D Vision (3DV), 654-662, 2019.

2018

Journal Articles

[J1] E Vespa, N Nikolov, M Grimm, L Nardi, PH Kelly and S Leutenegger,
Efficient octree-based volumetric SLAM supporting signed-distance and occupancy mapping,
IEEE Robotics and Automation Letters, 3(2): 1144-1151, 2018.